ST3-4040 ST6-4050

ST6-4060 ST6-4070



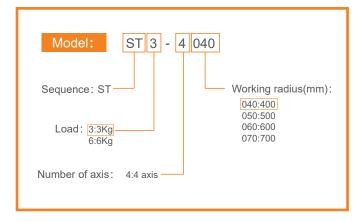
The series of industrial robots are multi joint, multi degree of freedom robots, flexible action, compact structure, easy to install and configure. It has the advantages of short stabilization time, good dynamic performance and high motion repeatability. The body adopts internal wiring, and the joint adopts modular design and assembly. It is easy to maintain and can effectively replace the light manual operation below 6kg.

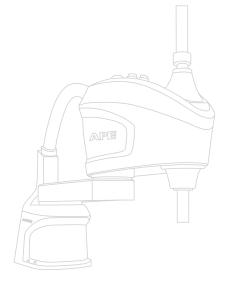
Typical Applications

- Electric welding
- Belt tracking
- Feeding and unloading
- Component assembly
- Cut off device
- Visual inspection
- Measurement distribution
- Material handling

Features

- · High precision, accurate and rapid identification of materials
- · Small installation space and fast running speed
- · It has high flexibility and versatility
- · Multiple complex movements can be realized
- · It can coordinate with multiple manipulators at the same time





• PAGE 03 •

Horizontal Multi-articulated Robot

APE Robot Series

Horizontal Multi-articulated Robot

ST6-4070



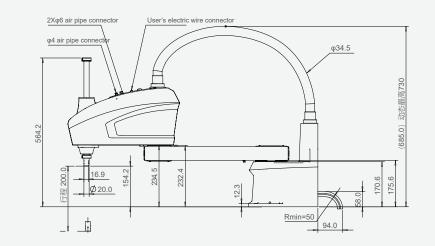
Performance Parameters

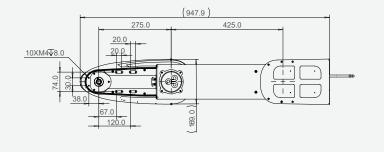
Item			ST6-4070
Mounting mode			Desktop
Configuration			Horizontal multi-articulated robot
Degree of freedom of motion			4
Drive motor			AC servo motor
Payload	Weight	Rated	2Kg
		Max.	6Kg
	Allowable inertial moment of joint #4	Rated	0.011Kg.m²
		Max.	0.13Kg.m²
Max. downforce of J3 axis			150N
Power of each motion axis	J1		400W
	J2		200W
	J3		100W
	J4		100W
Arm length	Primary arm		425mm
	Secondary arm		275mm
Max. reachable radius			700mm
Working space	J1		±122°
	J2		±145°
	J3		200mm
	J4		±720°
Max. speed	J1+J2		6.8m/s
	J3		0.925m/s
	J4		1875deg/s
Standard cycle time *1			0.47s
Repeated positioning accuracy	J1+J2		±0.02mm
	J3		±0.01mm
	J4		±0.01°
Main unit weight (excl. cables)			25Kg
User electric circuit			15 Pin D-sub
User air circuit			ф4mmx1, ф6mmx2
Environmental specification			IP20

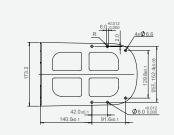
^{*1:} Movement time refers to the shortest time that under rated load, it moves back and forth in a range of 300mm horizontally and 25mm vertically.

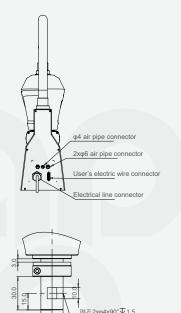
Motion range

Installation Dimension









The position shown in View A is the origin position of axis 3 and axis 4